

ALBERTO MOEL
amoel@alum.mit.edu

professional experience

2023-present	UNIVERSITY OF HONG KONG BUSINESS SCHOOL <i>Professor of Practice in Finance</i> - Developed and taught MBA course <i>Entrepreneurial Finance – Valuing, Financing, and Exiting Startups</i>. Also teaching the undergraduate corporate finance course. - Case development on entrepreneurial ecosystems and the Asian startup environment. - Case development on disruptive innovation in warehouse and factory automation. - Research and policy work on startups and startup ecosystems.	HONG KONG
2024-2025	SYMBOTIC, INC. <i>Vice President, Strategy and Partnerships, FreeMove</i> - Contract position for post-merger integration after acquisition of Veo Robotics by Symbotic, Inc. - Continued development of FreeMove intellectual property.	WALTHAM, MA
2017-2024	VEO ROBOTICS <i>Vice President, Strategy and Partnerships</i> - Deep-tech startup making industrial robots collaborative (www.veobot.com). Responsible for industry partnerships and relationships, thought leadership, intellectual property, market intelligence, and overall company strategy. - Key person in fundraising and investor relationships. - Helped company raise over \$60 million in funding from GV (Google Ventures), Lux Capital, Alpha Intelligence Capital, Amazon Robotics, Yamaha Motors, Next47 (Siemens Ventures), Baidu Ventures, SBI Group, Nikon, and other investors. - Acquired by Symbotic, Inc (www.symbotic.com).	WALTHAM, MA
2010-2017	BERNSTEIN RESEARCH <i>Director, Vice President, and Senior Research Analyst</i> Research Analyst for Asian technology sector, focusing on investment opportunities in automation and robotics, flat panel displays, display glass, manufacturing supply chain, and PC OEMs. - Joined Bernstein's Hong Kong office as a startup, with limited infrastructure and capabilities, #3 hire in Hong Kong. Office currently has 60+ staff. - Substantially involved in hiring, recruiting, business development and client acquisition, in addition to building tech research franchise into respected source of information and insight. - Spent more than 50% of time on the ground with manufacturing technology end users, suppliers, and industry participants. Viewed by clients and industry participants as a resource and authority in robotics and automation, manufacturing technology, and display technology. - Authored or co-authored over 600 company reports, research notes, in-depth-valuations, and investment recommendations. Was the main author or co-author on 30 Bernstein Black Book in-depth analyses aimed at professional investment managers.	HONG KONG
2004-2010	MONITOR GROUP <i>Principal</i> Co-leader of the Tokyo Office, responsible for lead generation, consultative selling, closing, and delivery of projects. Specializing in work at the intersection of finance and technology strategy. Advised a major Korean consumer electronics manufacturer on investment planning, technology strategy, product portfolio, and business model strategy for flat panel displays.	HONG KONG and TOKYO

	- Advised strategic and financial entities in consumer electronics, semiconductors, and flat-panel displays on diverse topics such as B2B go-to-market strategies, value chain rationalization, technology strategy, acquisition programs, and large-scale investment planning. - Worked with Japanese and pan-Asian asset management and financial services firms on corporate strategy, acquisitions, risk management, and consumer understanding.	
2003-2004	HONG KONG UNIVERSITY OF SCIENCE AND TECHNOLOGY <i>Assistant Professor of Finance</i> - Taught courses on Investments and Corporate Finance in the MBA and Executive MBA program. - Carried out research in expectations and stock returns, and on cross-border investments. - Published research in top-ranked finance and accounting journals.	HONG KONG
2001-2003	MONITOR GROUP <i>Principal, Monitor Corporate Finance</i> Consultant to senior management of corporate clients, specializing in work at the intersection of finance and technology strategy. Main areas of client engagement: - Helped US-based investor group negotiate with Eastern European sovereign regarding impaired assets in the broadcasting industry. - Worked with major UK, Canadian, US, Brazilian, and South African oil and gas, mining and raw materials concerns on investment decision-making, acquisition and joint-venture strategies.	CAMBRIDGE, MA and HONG KONG
1999-2001	AAA ASSET MANAGEMENT <i>Managing Partner and Director of Research</i> General partner in fund that invests in Brazilian equity and fixed income instruments. Developed synthetic fixed income, alpha-transfer, market-neutral and market-timing trading strategies, and general asset allocation models. Responsible for fundraising, hiring, building research and trading infrastructure.	SÃO PAULO, BRAZIL
1997-2000	HARVARD UNIVERSITY GRADUATE SCHOOL OF BUSINESS ADMINISTRATION <i>Lecturer in Finance</i> Taught required First Year Finance and Quantitative Methods courses in the MBA program. Published research in top-ranked finance journals such as <i>Journal of Financial Economics</i> and <i>Review of Financial Studies</i> .	BOSTON, MA
1996-1997	<i>Charles M. Williams Fellow, Finance Department</i> Carried out research and course development in Finance with Peter Tufano, Ken Froot, and Robert C. Merton.	
1995	JP MORGAN AND COMPANY <i>Global Markets/Emerging Markets Sales, Trading, and Research Summer Associate</i> Analyzed the opening of a JP Morgan broker (Casa de Bolsa) in Mexico City. Managed the Casa de Bolsa startup process. Developed swap pricing and valuation models for local market IR and currency swaps.	NEW YORK, NY and MEXICO CITY
1992-1994	TOSHIBA CORPORATION ULSI RESEARCH CENTER <i>R&D Staff Member</i> Determined fabrication budget and process specifications for advanced semiconductor memory manufacturing. Worked on technology transfer for fab pilot lines, and managed product development cycle for 1 GB DRAM memories. Built semiconductor manufacturing tools.	KAWASAKI, JAPAN

MASSACHUSETTS INSTITUTE OF TECHNOLOGY**CAMBRIDGE, MA**

1988-1992

Research Assistant and Teaching Assistant

Researched x-ray lithography in MIT's Submicron Structures Laboratory. Fabricated x-ray masks, constructed precision machinery and equipment, and x-ray sources.

1985-1986

Undergraduate Researcher

Developed and implemented computer control and communications system for underwater Remotely Operated Vehicle (ROV). Tested ROV in Boston Harbor and open waters.

INTERNATIONAL BUSINESS MACHINES

1987

Scientific Staff Member, IBM Zurich Research Lab & IBM Cambridge Scientific Center.

Carried out experimental work in Scanning Tunneling Microscopy. Worked with 1986 Physics Nobel Prize winners. Worked on STM technology transfer to production line toolset. Designed and implemented an antialiasing zoom algorithm for high performance graphics processor.

1985-1987

Researcher, IBM T.J. Watson Research Center

Developed robust, factory-ready acquisition, control, and image processing system for Scanning Tunneling Microscope. Carried out experimental work in Scanning Tunneling Microscopy. Developed experimental PC-Local Area Network/Mainframe gateway server.

other professional experience

Limited Partner and advisor in VC funds, direct investment in hardware, IoT, and robotics startups.

Mentor, Deep Tech Lab (<https://www.hkdeeptechlab.com/>), 2026-present

Senior Advisor, EQT, 2026-present

Selection Committee, The Asia Technology Entrepreneurship Conference (ATEC), 2025-present.

Steering Committee, Boston University Questrom Business of AI Research Initiative, 2025-present.

Expert Mentor, Singapore-MIT Alliance for Research and Technology (SMART), 2023-present.

Mentor, METI J-StarX program and Hiroshima Launchpad, 2023-present.

Advisor, MindMics, 2022.

Advisor, Alpha Intelligence Capital, 2017-present.

Expert in Residence, Q Ventures Fund, 2017-present.

Instructor, HBX "Leading with Finance" course, 2016.

Mentor, MIT Hong Kong Innovation Node, 2016-2018.

Mentor, Lane Crawford Cage.io accelerator program, 2016-2018.

Director, Eastspring Asset Management Japan, 2007-2010.

Partner, MMO y Asociados, Guadalajara, Mexico, 2001-2008. Specialized in principal investment, turnaround management, and financial advisory for Mexican middle-market companies.

Instructor, FGV-YPO Program, São Paulo, Brazil, 2002.

Visiting Professor, IDE, Ecuador, 2001.

Advisor, Global Project Design, San Francisco, CA, 2000-present.

Director, ATR, S.A., Guadalajara, Mexico, 1999-2002.

Advisor, Altgate Capital, New York and London, 1999-2001.

Instructor, IPADE, Mexico City, 1999-2000.

Instructor, Allen Resources, CFA Level II and Level III Training, 2000-2002.

Instructor, Violy, Byorum & Partners, New York, 1999.

Instructor, Bank of Nova Scotia/Inverlat Mexico City, 1997-1998.

Instructor, ABN-AMRO Bank Brazil Capital Markets program, São Paulo, Brazil, 1998.

Instructor, JP Morgan Training Program, New York, 1997.

Director, Harvard Cooperative Society, 1994-2004. Finance and Executive Committees.

education

HARVARD UNIVERSITY GRADUATE SCHOOL OF BUSINESS ADMINISTRATION

BOSTON, MA

- 1996-1999 Completed doctoral-level courses in Finance, Economics, and Econometrics as non-degree student.
- 1994-1996 Master in Business Administration degree, June 1996. Graduated with High Distinction (Baker Scholar, top 5% of class).

MASSACHUSETTS INSTITUTE OF TECHNOLOGY

CAMBRIDGE, MA

- 1990-1992 Doctor of Science in Electrical Engineering degree, February 1993. Thesis title: "An Aligner for X-ray Nanolithography." Minor in Digital Signal Processing.
- 1988-1990 Electrical Engineer Degree. Granted for additional coursework and research in the area of micromechanics.
- 1987-1988 Master of Science Degree, February 1988. Thesis title: "Real-time Control, Acquisition, and Image Processing for the Scanning Tunneling Microscope."
- 1983-1986 Bachelor of Science in Electrical Engineering, June 1986. Thesis title: "VMCS: A PC-Network to VM System Gateway Server." Application of thesis work to underwater remotely operated vehicles. Enrolled in MIT VI-A Electrical Engineering Internship Program.

honors

- 1996 *George F. Baker Scholar.* Given for extraordinary academic achievement in Harvard MBA, top 5% of graduating class.
- 1990 *MIT 10K Entrepreneurial Competition finalist.* Third-place finisher.
- 1990 *MIT Japan Program Prize winner.*
- 1989-1990 *IBM Graduate Fellow in Materials and Devices.*
- 1985-1986 *Two-time Sea Grant scholarship winner.* Given for work in development of underwater robotics systems.

other

Fluent in Spanish and English. Highly proficient in Japanese (passed highest level of Japanese Language Proficiency Test). Proficient in French and Portuguese. Widely quoted in mainstream media such as Wall Street Journal, Bloomberg, Reuters, and South China Morning Post as a technology analyst. Guest on multiple technology and China-focused podcasts.

patents: granted

US Patent No. 5,414,514. H. I. Smith, A. Moel, and E.E. Moon. On-axis interferometric alignment of plates using the spatial phase of interference patterns. Patent licensed to Canon, Inc., and to Lumarray, Inc.

US Patent No. 10,099,372. C. Vu, S. Denenberg, P. Sobalvarro, P. Barragan, and A. Moel. Detecting and classifying workspace regions for safety monitoring. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 10,882,185. C. Vu, S. Denenberg, P. Sobalvarro, P. Barragan, and A. Moel. Dynamically determining workspace safe zones with speed and separation monitoring. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 10,887,578. S. Denenberg, L. Persits, C. Vu, R. Randall, P. Sobalvarro, V. Chamorro, G. Malkin, and A. Moel. Depth-sensing computer vision system. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 10,887,579. S. Denenberg, L. Persits, C. Vu, R. Randall, P. Sobalvarro, V. Chamorro, G. Malkin, and A. Moel. Depth-sensing computer vision system. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 10,899,007. C. Vu, S. Denenberg, P. Sobalvarro, P. Barragan, and A. Moel. Ensuring safe operation of industrial machinery. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,040,450. C. Vu, S. Denenberg, P. Sobalvarro, P. Barragan, and A. Moel. Dynamically determining and monitoring workspace safe zones using semantic representations of workpieces. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,097,422. S. Denenberg, P. Sobalvarro, C. Vu, A. Moel, and R. Kelsey. Safety-rated multi-cell workspace mapping and monitoring. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,156,981. D. Dedkov, S. Denenberg, I. Kriveshko, P. Schroeder, C. Vu, P. Sobalvarro, and A. Moel. Systems and methods for automatic sensor registration and configuration. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,254,004. S. Denenberg, B. Mello, M. Galligan, C. Vu, P. Sobalvarro, M. Wartenberg, and A. Moel. System identification of industrial robot dynamics for safety-critical applications. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,256,241. P. Sobalvarro, C. Vu, J. Downer, P. Ferreira, M. A. Guney, T. C. Ferree, A. Moel, and R. Kelsey. Optimized factory schedule and layout generation. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,279,039. C. Vu, S. Denenberg, P. Sobalvarro, P. Barragan, and A. Moel. Detecting and classifying workspace regions for safety monitoring. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,376,741. C. Vu, S. Denenberg, P. Sobalvarro, P. Barragan, and A. Moel. Dynamically determining workspace safe zones with speed and separation monitoring. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,396,099. M. Wartenberg, P. Schroeder, B. Mello, C. Vu, S. Denenberg, N. Aucoin, and A. Moel. Safe operation of machinery using potential occupancy envelopes. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,543,796. D. Dedkov, S. Denenberg, I. Kriveshko, P. Schroeder, C. Vu, P. Sobalvarro, and A. Moel. Systems and methods for automatic sensor registration and configuration. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,543,798. S. Denenberg, C. Vu, P. Sobalvarro, L. Persits, I. Kriveshko, E. Simon, A. Moel, P. Foy, and J. Bronder. System architecture for safety applications. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,613,017. S. Denenberg, P. Sobalvarro, C. Vu, A. Moel, and R. Kelsey. Safety- rated multi-cell workspace mapping and monitoring. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,635,749. P. Sobalvarro, C. Vu, J. Downer, P. Ferreira, M. A. Guney, T. C. Ferree, A. Moel, and R. Kelsey. Optimized factory schedule and layout generation. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,679,504. S. Denenberg, C. Vu, G. Malkin, L. Persits, V. Chamorro, M. Wartenberg, P.D. Dalvi, and A. Moel. Crosstalk mitigation for multi-cell workspace monitoring. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,766,780. S. Denenberg, B. Mello, M. Galligan, C. Vu, P. Sobalvarro, M. Wartenberg, and A. Moel. System identification of industrial robot dynamics for safety-critical applications. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,820,025. C. Vu, S. Denenberg, P. Sobalvarro, and A. Moel. Safe motion planning for machinery operation. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,846,916. S. Denenberg, C. Vu, P. Sobalvarro, L. Persits, I. Kriveshko, E. Simon, A. Moel, P. Foy, and J. Bronder. System architecture for safety applications. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,919,173. S. Denenberg, C. Vu, P. Sobalvarro, and A. Moel. Motion planning and task execution using potential occupancy envelopes. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 11,945,119. S. Denenberg, C. Vu, G. Malkin, L. Persits, V. Chamorro, M. Wartenberg, P.D. Dalvi, and A. Moel. Crosstalk mitigation for multi-cell workspace monitoring. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 12,036,683. C. Vu, S. Denenberg, P. Sobalvarro, and A. Moel. Safe motion planning for machinery operation. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 12,049,014. C. Vu, S. Denenberg, M. Wartenberg, P. Schroeder, I. Kriveshko, and A. Moel. Workplace monitoring and semantic entity identification for safe machine operation. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

US Patent No. 12,301,778. S. Denenberg, L. Persits, C. Vu, R. Randall, P. Sobalvarro, V. Chamorro, G. Malkin, and A. Moel. Depth-sensing computer vision system. Patent assigned to Symbotic, LLC.

US Patent No. 12,420,419. S. Denenberg, C. Vu, P. Sobalvarro, and A. Moel. Motion planning and task execution using potential occupancy envelopes. Patent assigned to Symbotic, LLC.

US Patent No. 12,330,311. C. Vu, S. Denenberg, M. Wartenberg, I. Kriveshko, A. Fiol-Mahon, and A. Moel. Intelligent monitoring of entry points in multi-cell workspaces. Patent assigned to Symbotic, LLC.

US Patent No. 12,397,434. C. Vu, S. Denenberg, P. Sobalvarro, and A. Moel. Safe motion planning for machinery operation. Patent assigned to Symbotic, LLC.

US Patent No. 12,452,396. C. Vu, A. Moel, S. Denenberg, M. Wartenberg, and E. Cobane. A sensor for safe detection of intrusions in a 3D volume. Patent assigned to Symbotic, LLC.

US Patent No. 12,596,346. C. Vu, A. Lewis, A. Fiol-Mahon, U.M. Erdem, P. Foy, I. Kriveshko, S. Denenberg, and A. Moel. Systems and methods for information-assisted sensor registration. Patent assigned to Symbotic, LLC.

US Patent No. 12,703,096. S. Denenberg, C. Vu, P. Sobalvarro, and A. Moel. Motion planning and task execution using potential occupancy envelopes. Patent assigned to Symbotic, LLC.

US Patent No. 12,643,237. C. Vu, S. Denenberg, M. Wartenberg, P. Schroeder, I. Kriveshko, and A. Moel. Workplace monitoring and semantic entity identification for safe machine operation. Patent assigned to Symbotic, LLC.

European Patent No. 3580735. C. Vu, S. Denenberg, P. Sobalvarro, P. Barragan, and A. Moel. Workspace safety monitoring and equipment control. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

European Patent No. 3844948. S. Denenberg, L. Persits, C. Vu, R. Randall, P. Sobalvarro, V. Chamorro, G. Malkin, and A. Moel. Depth-sensing computer vision system. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

European Patent No. 3887101. S. Denenberg, C. Vu, P. Sobalvarro, L. Persits, I. Kriveshko, E. Simon, A. Moel, P. Foy, and J. Bronder. System architecture for safety applications. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

European Patent No. 3888306. S. Denenberg, P. Sobalvarro, C. Vu, A. Moel, and R. Kelsey. Safety-rated multi-cell workspace mapping and monitoring. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

European Patent No. 3844432. D. Dedkov, S. Denenberg, I. Kriveshko, P. Schroeder, C. Vu, P. Sobalvarro, and A. Moel. Systems and methods for automatic sensor registration and configuration. Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

European Patent No. 3843956. S. Denenberg, B. Mello, M. Galligan, C. Vu, P. Sobalvarro, M. Wartenberg, and A. Moel. System identification of industrial robot dynamics for safety-critical applications. Patent assigned to Symbotic, LLC.

Japanese Patent No. 6,898,012. C. Vu, S. Denenberg, P. Sobalvarro, P. Barragan, and A. Moel. 作業空間安全監視および機器制御 (Workspace safety monitoring and equipment control). Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

Japanese Patent No. 6,752,499. C. Vu, S. Denenberg, P. Sobalvarro, P. Barragan, and A. Moel. 作業空間安全監視および機器制御 (Workspace safety monitoring and equipment control). Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

Japanese Patent No. 7,122,776. C. Vu, S. Denenberg, P. Sobalvarro, P. Barragan, and A. Moel. 作業空間安全監視および機器制御 (Workspace safety monitoring and equipment control). Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

Japanese Patent No. 7,136,507. S. Denenberg, L. Persits, C. Vu, R. Randall, P. Sobalvarro, V. Chamorro, G. Malkin, and A. Moel. 深度感知コンピュータビジョンシステム (Depth-sensing computer vision system). Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

Japanese Patent No. 7,262,847. S. Denenberg, B. Mello, M. Galligan, C. Vu, P. Sobalvarro, M. Wartenberg, and A. Moel. 安全重視用途に関する産業ロボット動力学のシステム識別 (System identification of industrial robot dynamics for safety-critical applications). Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

Japanese Patent No. 7,299,642. D. Dedkov, S. Denenberg, I. Kriveshko, P. Schroeder, C. Vu, P. Sobalvarro, and A. Moel. 自動的センサ位置合わせおよび構成のためのシステムおよび方法 (Systems and methods for automatic sensor registration and configuration). Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

Japanese Patent No. 7,319,001. I. Kriveshko, P. Schroeder, M. Wartenberg, B. Mello, C. Vu, S. Denenberg, A. Feldman, M. Galligan, P. Sobalvarro, N. Aucoin, and A. Moel. 潜在的占有エンベロープを使用した機械類の安全動作 (Safe operation of machinery using potential occupancy envelopes). Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

Japanese Patent No. 7,378,168. S. Denenberg, C. Vu, P. Sobalvarro, L. Persits, I. Kriveshko, E. Simon, A. Moel, P. Foy, and J. Bronder. 安全用途のためのシステムアーキテクチャ (System architecture for safety applications). Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

Japanese Patent No. 7,448,246. S. Denenberg, L. Persits, C. Vu, R. Randall, P. Sobalvarro, V. Chamorro, G. Malkin, and A. Moel. 深度感知コンピュータビジョンシステム (Depth-sensing computer vision system). Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

Japanese Patent No. 7,505,791. S. Denenberg, P. Sobalvarro, C. Vu, A. Moel, and R. Kelsey. 安全定格マルチセル作業空間マッピングおよび監視 (Safety-rated multi-cell workspace mapping and monitoring). Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

Japanese Patent No. 7,649,064. S. Denenberg, C. Vu, P. Sobalvarro, L. Persits, I. Kriveshko, E. Simon, A. Moel, P. Foy, and J. Bronder. 安全用途のためのシステムアーキテクチャ (System architecture for safety applications). Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

Chinese Patent No. 112640447. S. Denenberg, L. Persits, C. Vu, R. Randall, P. Sobalvarro, V. Chamorro, G. Malkin, and A. Moel. 深度感测计算机视觉系统 (Depth-sensing computer vision system). Patent assigned to Veo Robotics, reassigned to Symbotic, LLC.

Chinese Patent No. 114296101. S. Denenberg, L. Persits, C. Vu, R. Randall, P. Sobalvarro, V. Chamorro, G. Malkin, and A. Moel. 深度感测计算机视觉系统 (Depth-sensing computer vision system). Patent assigned to Symbotic, LLC.

Chinese Patent No. 114721007. S. Denenberg, L. Persits, C. Vu, R. Randall, P. Sobalvarro, V. Chamorro, G. Malkin, and A. Moel. 深度感测计算机视觉系统 (Depth-sensing computer vision system). Patent assigned to Symbotic, LLC.

patents: pending

CA 3052961. C. Vu, S. Denenberg, P. Sobalvarro, P. Barragan, and A. Moel. Workspace safety monitoring and equipment control.

CN 110494900. C. Vu, S. Denenberg, P. Sobalvarro, P. Barragan, and A. Moel. 工作空间安全监控和设备控制 (Workspace safety monitoring and equipment control).

EP 3980853. I. Kriveshko, P. Schroeder, M. Wartenberg, B. Mello, C. Vu, S. Denenberg, A. Feldman, M. Galligan, P. Sobalvarro, N. Aucoin, and A. Moel. Safe operation of machinery using potential occupancy envelopes.

EP 4052866. I. Kriveshko, P. Schroeder, M. Wartenberg, B. Mello, C. Vu, S. Denenberg, A. Feldman, M. Galligan, P. Sobalvarro, N. Aucoin, and A. Moel. Safe operation of machinery using potential occupancy envelopes.

EP 4052867. I. Kriveshko, P. Schroeder, M. Wartenberg, B. Mello, C. Vu, S. Denenberg, A. Feldman, M. Galligan, P. Sobalvarro, N. Aucoin, and A. Moel. Safe operation of machinery using potential occupancy envelopes.

EP 4088890. C. Vu, S. Denenberg, P. Sobalvarro, P. Barragan, and A. Moel. Workspace safety monitoring and equipment control.

EP 4088891. C. Vu, S. Denenberg, P. Sobalvarro, P. Barragan, and A. Moel. Workspace safety monitoring and equipment control.

EP 4250753. S. Denenberg, L. Persits, C. Vu, R. Randall, P. Sobalvarro, V. Chamorro, G. Malkin, and A. Moel. Depth-sensing computer vision system.

EP 4446069. S. Denenberg, P. Sobalvarro, C. Vu, A. Moel, and R. Kelsey. Safety-rated multi-cell workspace mapping and monitoring.

JP 2024-056983. S. Denenberg, L. Persits, C. Vu, R. Randall, P. Sobalvarro, V. Chamorro, G. Malkin, and A. Moel. 深度感知コンピュータビジョンシステム (Depth-sensing computer vision system).

US 2022/0234209. I. Kriveshko, M. Wartenberg, C. Vu, S. Denenberg, N. Aucoin, and A. Moel. Safe operation of machinery using potential occupancy envelopes.

US 2024/0036545. S. Denenberg, C. Vu, P. Sobalvarro, L. Persits, I. Kriveshko, E. Simon, A. Moel, P. Foy, and J. Bronder. System architecture for safety applications.

publications: robotics

“China is falling behind at the sharp end of the global robot race”, *The Wire China*, 2025. <https://www.thewirechina.com/2025/12/17/china-is-falling-behind-at-the-sharp-end-of-the-global-robot-race-china-industrial-advanced-robotics/>

“Implementing effective Speed and Separation Monitoring with legacy industrial robots – state of the art, issues, and the way forward”, (with Scott Denenberg and Marek Wartenberg), 2021, in *The 21st Century Industrial Robot - When Tools become Collaborators*, edited by M. I. Aldinhas Ferreira and S. R. Fletcher (Springer). https://doi.org/10.1007/978-3-030-78513-0_13. Author or co-author of regular blog series on robotics, automation, and the future of work.

publications: finance

“Rebuilding Hong Kong as the catalyst to the Greater Bay Area (GBA) startup ecosystem”, 2026, in *Hong Kong Economic Policy Green Paper 2026*, HKU Business School.

“Understanding the Hong Kong startup ecosystem: a framework and future directions”, 2025, in *Hong Kong Economic Policy Green Paper 2025*, HKU Business School.

Authored or co-authored over 600 company reports and research notes on Asian IT hardware (displays, display glass, automation and robotics, PCs, and electronics manufacturing), and was main author or co-author on 30 Bernstein Black Book in-depth analyses aimed at professional investment managers.

“Czech mate: Expropriation and investor protection in a converging world”, (with Mihir Desai), 2008. *Review of Finance* 12, p. 221-251. Presented at the ECGI Corporate Governance Symposium (2005), European Finance Association Meeting, Moscow (2005), Batten Institute Emerging Markets Finance Conference (2005). Third-place winner, ECGI Corporate Governance Competition, 2005. Abstracted in *Beyond Transition* (15:1), World Bank, Oct/Nov/Dec 2004.

“The role of expectations in explaining the cross-section of stock returns”, (with Tom Copeland and Aaron Dolgoff), 2004. *Review of Accounting Studies* 9, p. 149-188. Presented at Harvard Business School (2002), UC Berkeley (2003), New York University (2003), RAST Conference (2003).

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